

NATIONAL UNIVERSITY OF SINGAPORE

PC5215 – NUMERICAL RECIPES WITH APPLICATIONS

(Semester I: AY 2015-16)

Time Allowed: 2 Hours

INSTRUCTIONS TO CANDIDATES

1. Please write your student number only.
2. This examination paper contains FIVE questions and comprises THREE printed pages.
3. Answer ALL the questions; questions carry equal marks.
4. Answers to the questions are to be written in the answer books.
5. Please start each question on a new page.
6. This is a CLOSED BOOK assessment.
7. Non-programmable calculators are allowed.

1. The IEEE 754 single precision floating-point format has one sign bit at the most significant position, followed by 8-bit for the biased exponent with a bias of 127, followed by 23-bit for the fractional part (mantissa).
 - a. Consider the following binary calculation of the floating point values, $z = x + y$, where $x = 0011\ 1110\ 1000\ 0000\ 0000\ 0000\ 0000\ 0000$,
 $y = 1011\ 1110\ 0111\ 1111\ 1111\ 1101\ 0110\ 0001$.
 Determine z as bit pattern.
 - b. Determine the absolute errors in x and y due to finite representation of real numbers in floating-point format. Determine the error in the result z , and give the number of significant figures in z (number of meaningful figures in decimal not counting leading zeros).
 - a) *The numerical value of x is 0.25, and y is -0.24999, but we don't need to know. The important point is that when adding/subtracting, the exponent of one of them must be shifted so that they have the same exponent, the result is $z = 0\ 0110\ 1110\ 010\ 011110xxx\dots$. The xxx means whose digits we don't know and it is part of the error in z .*
 - b) *Absolute errors are 1.5×10^{-8} , and 7×10^{-9} , 3×10^{-8} , for x , y , z , respectively. The number of significant figures of z is at most 9 in binary and 3 in decimal. Due to the closeness of x and $|y|$, subtraction causes a great loss of accuracy.*

2. Páde approximation is similar to polynomial interpolation except that it is given by the ratio of two polynomials, for example,

$$e^x = 1 + x + \frac{x^2}{2} + \dots \approx \frac{c_0 + c_1 x + \dots + c_N x^N}{1 + d_1 x + \dots + d_M x^M}.$$

- a. Determine the coefficients of the right-hand side when $N = M = 1$.
- b. Give a general method (algorithm) to determine the coefficients c_i and d_j .

Hint: multiply the denominator to the left-side, and match the coefficients of the polynomials.

a) The answer is $\exp(x) \approx (1+x/2)/(1-x/2)$. b) We have $N+M+1$ unknowns. We need form sufficient equations to determine them uniquely, so the expansion should not stop, but up to $x^{(N+M)}$ with the power larger than N set to 0. See also NR book Chap.3.2, Chap.5.12.

3. The following pseudo C code is written for a Monte Carlo simulation of the one-dimensional Ising model with the Hamiltonian $H(\sigma) = -J \sum_{i=1}^N \sigma_i \sigma_{i+1}$, with periodic boundary condition, e.g., $\sigma_{N+1} = \sigma_1$. Based on the code, determine the transition matrix W of the Markov chain and its equilibrium distribution p , such that $p = pW$.

$i =$ a random integer from 1 to N ;

$\Delta = (2J/k_B T) (\sigma_{i-1} + \sigma_{i+1})$;

$r = e^{-\Delta} / (1 + e^{-\Delta})$;

$$\sigma_i = \text{sign}(\xi - r);$$

where k_B is the Boltzmann constant, T is temperature, $J > 0$ is the ferromagnetic coupling constant, ξ is a uniformly distributed random number from 0 to 1, and i , Δ , and r are temporary variables. $\text{sign}(x)$ is the sign function taken value 1 if $x > 0$ and -1 otherwise.

The program says that we set the spin up (+1) with probability $1-r$, and down (-1) with probability r . This means we don't care about the value of the spins before flip so it is not Metropolis. The transition matrix W (which is a 2^N by 2^N matrix) consists of two parts, the part $T(\sigma \rightarrow \sigma')$ which denotes the selection of the spins at random, so T is $1/N$ if two states differ by one spin, and zero otherwise. The rate part is (fixing all other spins and focus only on site i , $\begin{pmatrix} 1-r & r \\ 1-r & r \end{pmatrix}$), where entries are ordered according to +, -. Since $1-r$ is the conditional probability of being +, given the values of all other spins, and r is the conditional probability of being -, if the overall probability is the canonical distribution, it is clear $(\sigma) = \exp(-\beta H(\sigma)) / Z$. This method of Monte Carlo simulation is known as heat-bath algorithm, or Gibbs sampler.

4. Consider the problem of fitting a curve with the exponential form $f(x) = Ae^{-kx}$. By working with the natural logarithm of the function $\ln f$, instead of f , we can turn a nonlinear fit to a linear least-squares fit. Let (x_i, y_i) be the set of data points for x and f , with standard deviation in f as σ_i (assuming small), $i = 1, 2, \dots, N$.
 - a. Derive formulas for the parameters A and k .
 - b. Determine the errors (one standard deviation) in A and k .

Hint: The standard least-squares formulas for straight line fitting, $y = a + bx$, are $a = \frac{S_{xx}S_y - S_xS_{xy}}{\Delta}$, $b = \frac{SS_{xy} - S_xS_y}{\Delta}$, $\Delta = SS_{xx} - (S_x)^2$, $\sigma_a^2 = \frac{S_{xx}}{\Delta}$, $\sigma_b^2 = S/\Delta$, where $S = \sum 1/\sigma_i^2$, $S_x = \sum \frac{x_i}{\sigma_i^2}$, etc.

We transform the problem into standard linear fit form. First, if the error in f is σ_i the error in $\ln f$ is σ_i/f , so we need to change all σ_i in the standard formulas to σ_i/y_i . The rest is easy, $a \rightarrow \ln A$, $b \rightarrow -k$. For the error in k , the formula work as it is. But for error in A , we need to use the error propagation formula to obtain A times the standard formula $\sqrt{S_{xx}/\Delta}$.

5. A harmonic oscillator subject to a random noise has the equations of motion for the position x and momentum p given by

$$\begin{aligned} \frac{dx}{dt} &= \frac{p}{m} \\ \frac{dp}{dt} &= -m\omega^2 x - \gamma p + \xi(t). \end{aligned}$$

Here m is particle mass, ω is oscillator angular frequency, γ is damping coefficient, and $\xi(t)$ is random noise satisfying zero mean value and some variance to be determined.

- If there is no noise, $\xi(t)=0$, give the forward Euler's integration method to solve the equation numerically. Specify the local truncation error.
- If the noise is nonzero and is implemented as independent Gaussian random number at each time step, determine the variance of the random number such that equipartition theorem, $\langle \frac{p^2}{2m} \rangle = \frac{k_B T}{2}$ and $\langle \frac{m\omega^2 x^2}{2} \rangle = \frac{k_B T}{2}$, are recovered. Hint: in steady state, the energy of the oscillator, $\frac{p^2}{2m} + \frac{1}{2}m\omega^2 x^2$, is a constant on average.

a) Euler method $x_{n+1} = x_n + p_n h/m + O(h^2)$; $p_{n+1} = p_n + (-m\omega^2 x_n - \gamma p_n)h + O(h^2)$, which map the point (x_n, p_n) to (x_{n+1}, p_{n+1}) with an error of order h^2 , i.e., the local truncation error is of order h^2 . b) We assume $p_{n+1} = p_n + (-m\omega^2 x_n - \gamma p_n)h + \xi_n + O(h^2)$, where the variance of the gaussian random noise is to be determined. Let's compute the difference of kinetic + potential energy between two steps, $E_{n+1} - E_n$ to the order of accuracy, i.e., to order h only as the method already has error of $O(h^2)$, we get $E_{n+1} - E_n = -\gamma p_n^2 h/m + \xi_n^2/(2m) + O(h^2)$. This quantity should be zero on average. Taken the average over the noise, we get $\langle \xi^2 \rangle = 2\gamma \langle p^2 \rangle h = 2m\gamma k_B T h$.

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[WJS]