- 1
- (a) On the way up, the weight and the frictional force are both downward; on the way down, the weight is downward but the frictional force is upward. Therefore, there is a larger net force between t = 0 and  $t = t_1$  than between  $t = t_1$  and  $t = t_2$ , with a correspondingly larger acceleration. To cover the same distance, then, it takes a shorter time upwards than downwards.
- (b) The differential equation

$$\ddot{z}(t) = -g - \gamma \dot{z}(t)$$

with  $\dot{z}(t=0) = v_0$  and z(t=0) = 0 is solved by

$$\dot{z}(t) = -\frac{g}{\gamma} + \left(v_0 + \frac{g}{\gamma}\right) e^{-\gamma t},$$
  
$$z(t) = -\frac{gt}{\gamma} + \left(v_0 + \frac{g}{\gamma}\right) \frac{1 - e^{-\gamma t}}{\gamma}.$$

From  $\dot{z}(t_1) = 0$  and  $z(t_2) = 0$ , we get

$$1 + \frac{\gamma v_0}{g} = e^{\gamma t_1} = \frac{\gamma t_2}{1 - e^{-\gamma t_2}},$$

so that

$$\mathrm{e}^{\gamma t_1} = \,\mathrm{e}^{\frac{1}{2}\gamma t_2} \frac{\frac{1}{2}\gamma t_2}{\sinh(\frac{1}{2}\gamma t_2)} < \,\mathrm{e}^{\frac{1}{2}\gamma t_2} \,,$$

and  $t_2 > 2t_1$  follows.

2

- (a) *a* is a length, and *F* is a force.
- (b) Fa is an energy, and  $\sqrt{ma/F}$  is a time.
- (c) We have

$$\sqrt{|x|+a} - \sqrt{a} \cong \begin{cases} \frac{1}{2}\sqrt{x^2/a} & \text{for } |x| \ll a, \\ \sqrt{|x|} & \text{for } |x| \gg a, \end{cases}$$

so that

$$V(x) \cong \begin{cases} \frac{1}{4a} Fx^2 & \text{for} \quad |x| \ll a, \\ F|x| & \text{for} \quad |x| \gg a. \end{cases}$$

(d) For 
$$\frac{1}{2}m\omega^2 x^2 = \frac{1}{4a}Fx^2$$
 and  $T = \frac{2\pi}{\omega}$ , we get  $T = 2\pi\sqrt{\frac{2ma}{F}}$ .

(e) The turning points are at  $x = \pm x_1$  with  $E = V(x_1)$ . Then

$$T(E) = 2\int_{-x_1}^{x_1} \frac{\mathrm{d}x}{\sqrt{\frac{2}{m} \left[V(x_1) - V(x)\right]}} = 4\int_{0}^{x_1} \frac{\mathrm{d}x}{\sqrt{\frac{2}{m} \left[V(x_1) - V(x)\right]}}$$

We substitute  $x=(y^2+2y)a$ ,  $\mathrm{d} x=\mathrm{d} y\,2(y+1)a$ ,  $V(x)=Fay^2$ ,  $E=V(x_1)=Fay_1^2$  and get

$$T(E) = 4 \int_{0}^{y_1} \frac{\mathrm{d}y \, 2(y+1)a}{\sqrt{\frac{2}{m}Fa(y_1^2 - y^2)}} = 4\sqrt{\frac{2ma}{F}} \int_{0}^{y_1} \frac{\mathrm{d}y \, (y+1)}{\sqrt{y_1^2 - y^2}} \,.$$

With

$$\int_{0}^{y_{1}} \frac{\mathrm{d}y \, y}{\sqrt{y_{1}^{2} - y^{2}}} = -\sqrt{y_{1}^{2} - y^{2}} \bigg|_{y = 0}^{y_{1}} = y_{1}$$

 $\mathsf{and}$ 

$$\int_{0}^{y_1} \frac{\mathrm{d}y}{\sqrt{y_1^2 - y^2}} = \frac{1}{2}\pi \,,$$

this gives

$$T(E) = \sqrt{\frac{2ma}{F}} \left( 4\sqrt{\frac{E}{Fa}} + 2\pi \right).$$

3

(a) Since

$$\nabla \times F \stackrel{\circ}{=} \begin{pmatrix} 4\lambda z \\ 0 \\ 0 \end{pmatrix} \neq 0,$$

this force is not conservative.

(b) Since

$$\nabla \times F = \nabla \times (a^2 r - a a \cdot r) = a^2 \underbrace{\nabla \times r}_{=0} + a \times \underbrace{\nabla (a \cdot r)}_{=a} = 0,$$

this force is conservative, and the potential energy is

$$V(\mathbf{r}) = -\frac{1}{2}a^2r^2 + \frac{1}{2}(\mathbf{a} \cdot \mathbf{r})^2 = -\frac{1}{2}(\mathbf{a} \times \mathbf{r})^2.$$